

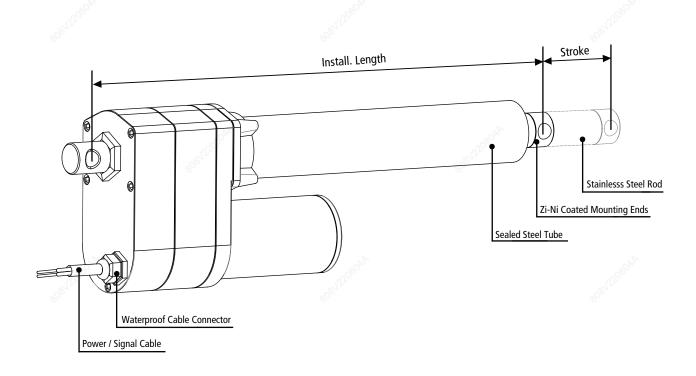
Dear Customers,

What a big world! But thanks to crazy technology, it's been getting smaller than ever, so that we can meet here from all corners of the world. It's our pleasure to have opportunities to provide you with a variety of products and services to help with the implementation of your amazing designs.

We present our products thoroughly in front of you by using refined parameters and words, so that you can find the most suitable solution.

Next, we will take you to a deeper understanding of Hongba's products. Please read this datasheet carefully. You are also welcome to leave valuable comments and suggestions to help Hongba improve itself continuously.

Definition of Terms



Stroke	How far the rod extends outwards from the body. The difference between fully extended length and fully retracted length. [Customizable]				
Install. Length	The fully closed size. [Customizable]				
Front Mount. End	Optional.				
Rear Mount. End	Optional.				
Mount. Holes	Can be rotated by 90°.				
Dynamic Force	The max force that actuator is able to carry when it is moving.				
Selflocking	The max force that linear actuator is able to hold when it stops.				
Weather Protection	IP XX. The first digit: dust protection. The second digit: liquid protection. Please refer to [Table 1].				
Duty Cycle	Continous working time 'a', rest time 'b'. Duty cycle is a/(a+b)x100%. Please refer to [Table 1].				
Speed	Include free-load speed and full-load speed.				
Hall Sensor	Provide pulse signals. Displacement measurement is achieved through pulse counting, and the phase difference of the waveform can be used to identify the rotation direction of motor. Check [Table 1] to see if it is available.				
Potentiometer	Potentiometer is a three-terminal variable resistor with a rotating contact which is used to measure the displacement of actuators. Check [Table 1] to see if it is available.				
Manual Override	Can be used to extend or retract the actuator without power for emergency. Check [Table 1] to see if it is available.				

Configs.

Color	□Silver	■ Black	\square Customized			
Lead Screw	Acme Screw	■ Ball Screw				
Operation Mode	■ Electrical	☐ Electrical + Manu	al			
Application	■ Industrial	□Furniture	\square Medical			
Operational Temp.	□5 to 40°C	■-10 to 65°C	■-40 to 65°C			
Operating Noise	□≤45 dB	□≤50 dB	■ ≤65 dB			
Stroke Range	■50-600mm	600-1,000mm		700		
Dynamic Load	□ ≤1,200N	□ ≤2,000N	□≤4,000N	■ ≤10,000N	☐ ≤12,000N	□≤20,000N
Duty Cycle	□10%	□ 20%	25% *	□50%	□ 100%	
Motor Type	■ Brushed DC	☐ Stepper Motor	\square Brushless	☐ Servo Motor		
Overload Protection	□None	Clutch	□Electronic	■ Thermistor		
Weather Protection	□IP20	□ IP43	□IP54	■ IP65	□ IP66	
Position Feedback	None	Endstop Signal	■ Hall Sensor	Potentiometer	☐ Encoder	☐ Reed Switches
Input Voltage	■12VDC	■24VDC	■36VDC	■ 48VDC	☐ 110VAC	□220VAC

^{*} Don't exceed four minutes continuous working at full load with 20 °C .

[Table 1]

Parameters

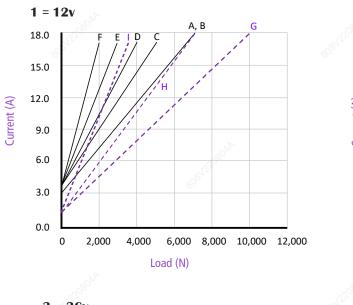
Fill in code:

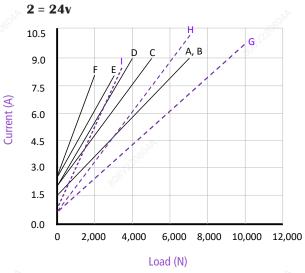
		② Max	May				(1)	Max. Stroke ^③	
Lead Screw	Code	Max. Dynamic Load	Max. Self- locking	Reduction Ratio	Pitch	Speed (mr	Speed±10% (mm/s)	w/o limit switch	limit switch with Pot or w/o Pot
	12280A.A	(N)	(N)	-	mm	Free Load	Full Load	mm	mm
8	Α	7,000	10,000	40:1	3.17	5.5	4	1,000	380
	В	7,000	10,000	40:1	5	8.5	7	1,000	610
Acme	С	5,000	7,000	20:1	3.17	11	9.5	1,000	380
Screw	D	4,000	5,500	20:1	5	17	14	1,000	610
	E	3,000	4,000	10:1	3.17	22	18	1,000	380
	F	2,000	2,800	10:1	5	35	28.5	1,000	610
	G	10,000	11,000	40:1	5	8.5	6.5	1,000	610
Ball Screw	Н	7,000	8,500	20:1	5	17	13.5	1,000	610
	A.P.	3,500	4,500	10:1	5	35	27	1,000	610

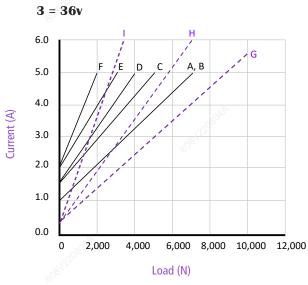
[Table 2]

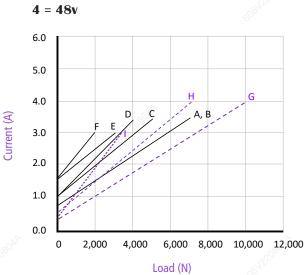
- ① Measurements are made with actuators in connection with stable power supplies and ambient temperature at 20°C.
- ② For example, when real load is 5000N, choosing code (C) is fine. Of course, you can also choose (B) or (A) which come with more load buffer, higher safety factor and longer product service time.
- ③ There are many factors affecting the "customizable maximum stroke", such as load, speed, force direction, etc., so the real application scenarios should be considered. If the parameters you required are not listed, please contact our sales engineers.
- 4 Potentiometer is not optional.

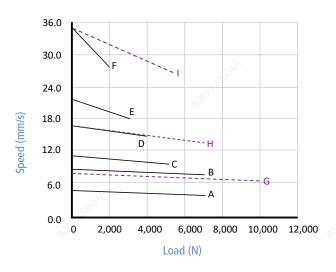
Charts Fill in code:









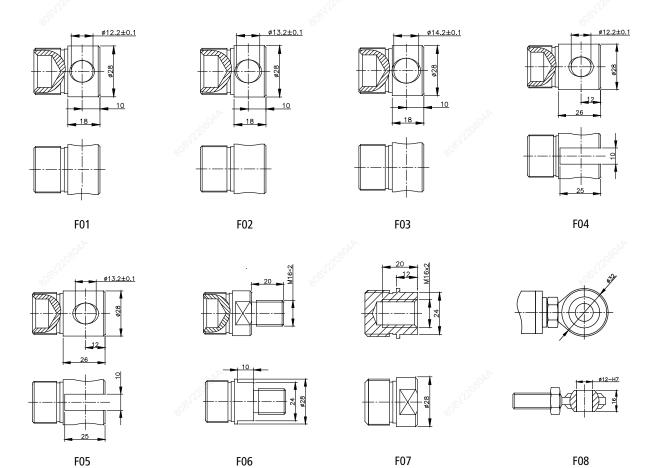


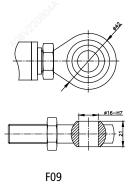
* Measurements are made with actuators in connection with stable power supplies and ambient temperature at 20°C.

Front Mounting End

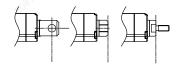
1. Please contact our sales team if none of the options below meet your requirements.

Fill in code:





2. Start of Installation Length

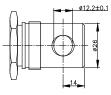


3. Hole Directions Fill in code: $1 = 90^{\circ}$ $2 = 0^{\circ}$

Rear Mounting End

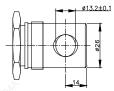
1. Please contact our sales team if none of the options below meet your requirements.

Fill in code:



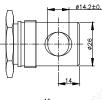


R01



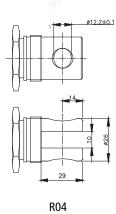


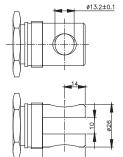
R02



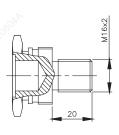


R03

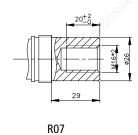




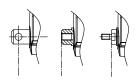
R05



R06



2. End of Installation Length



3. Hole Directions



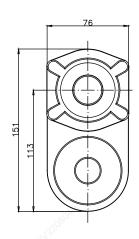
1 = 90°

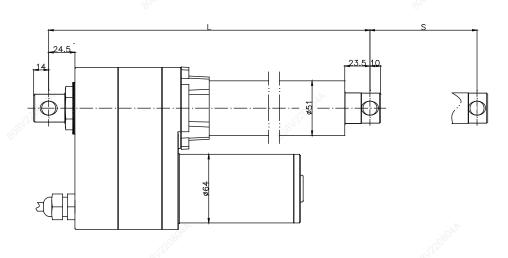


2 = 0°

Fill in code:

[Intergrated Limit Switches]





A. Mounting Ends VS Install. Length

	Rear Mount. Ends
Front Mount. Ends	R01, R02, R03, R04, R05, R06, R07
F01, F02, F03, F04, F05, F06, F07	A≥S+ 250mm
F08, F09	A≥S+ 300mm

[Table 3]

B. Stroke VS Install. Length

Stroke (S) (mm)	Install. Length (L) (mm)
50 - 399	+ 0
400 - 610	+ 50

[Table 4]

How to calculate 'Install. Length'?

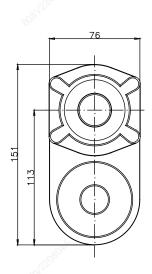
S = Stroke, L = Install Length, $L \ge A + B$

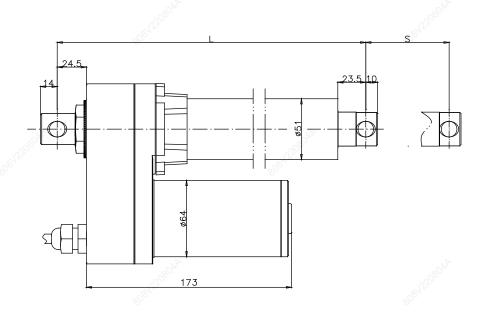
Example

Front	Rear	S	A	B	L≥A+B
Mount.	Mount.	(mm)	(mm)	(mm)	(mm)
F08	R01	300	300+300	+0	

[Table 5]

[Without Limit Switches]





A. Mounting Ends VS Install. Length

	Rear Mount. Ends
	S. S
	R01, R02,
Front Mount. Ends	R03, R04,
	R05, R06,
	R07
	75.80AL
	8027
F01, F02,	
F03, F04, F05, F06,	A≥S+ 200mm
F07	
	14000
	808 M
F08, F09	A≥S+ 250mm
100,103	NED 1 23011111

[Table 6]

B. Stroke VS Install. Length

Stroke (S) (mm)	Install. Length (L) (mm)
50 - 399	+ 0
≥ 400	+ 50

[Table 7]

How to calculate 'Install. Length'?

 $S = Stroke, \, L = \,\, Install \,\, Length, \,\, L \geq \,\, A \, + \, B$

Example

Front	Rear	S	А	В	L≥A+B
Mount.	Mount.	(mm)	(mm)	(mm)	(mm)
F08	R01	300	300+250	+0	≥550

[Table 8]

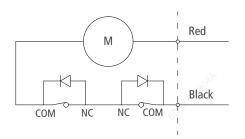
0 = None 1 = Endstop Signal

2 = Hall Sensor

3 = Potentiometer

0. Standard Limit Switches without Signal feedback

Standard DJ808 comes with limit switches that shut off the motor automatically at the end of its travel.

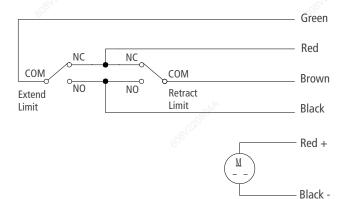


	Wiring					
	Black Red					
Extend	080g/z -	+				
Retract	+	-				

[Table 9]

1. Endstop Signal

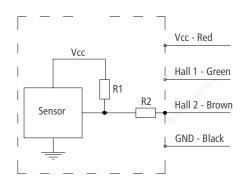
The actuator can be equipped with endstop signals output, but it will not auto-stop at neither end of the travel.

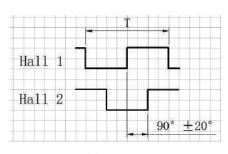


Power Wire Coding					
	Black	Red			
Extend	-	+			
Retract	+	-			
	Signal Wire Coding				
Black	Black Extend / Retract limit, N.O.				
Red Extend / Retract limit, N.C.					
Green	Green Extend limit. COM.				
Brown Retract limit. COM.					
[7 11 40]					

[Table 10]

2. Hall Sensor (standard dual-sensor)





* Power supply (V)= 5~15V

	Pulse Equivalent per Sensor (pulse/mi		
Code	1 pole pair	4 pole pairs (standard)	
A	12.6	50.5	
В	8.0	32.0	
С	6.3	25.2	
D	4.0	16.0	
E	3.2	12.6	
F	2.0	8.0	

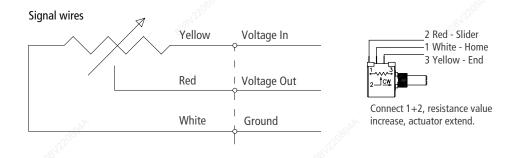
[Table 11]

3. Potentiometer

Code	Max. Stroke	Resistance Value per mm		
A, C, E	380 mm	0.0250 K Ω		
B, D, F	610 mm	0.0159 K Ω		

^{*} Start value 0.5±0.1K Ω

[Table 12]



RESET

Inquiry Table

			IVEDET			
30877	Voltage	1 = 12VDC 2 = 24VDC 3 = 36VDC 4 = 48VDC	908/15/16/8VA			
	Load & Speed	See [Table 2]				
	Stroke (mm)	Please contact us if the stroke you required is out of range. See Table [3] - [8] FO1 - FO9 FX = Custom				
	Install. Size (mm)					
	Front Mount. End					
	Rear Mount. End	R01 - R07 RX = Custom	3080h			
600	Mount. Hole Direction	***************************************				
	Signal Feedback	0 = None 1 = Endstop Signal 2 = Hall Sensor 3 = Potentiometer				
	Cable Length	1 = 400mm 2 = 1,000mm 3 = 2,000mm X = Custom				
	Connector	0 = Tinned bared wires $1 = Go with KZ control$ $X = Custom$				
	Working Temperture	1 = -10°C to 65°C	CAP.			
Ap	Working Frequency	Estimated cycles work per day	*08/15/201			
		Indoor or outdoor, and please describe your end use.				
	End Use					
Application		CAP SOL				
on	Your Contact	Company Name				
		Tel. Email				

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Wuxi Hongba Mechanical Electrical Equipment. Co., Ltd.

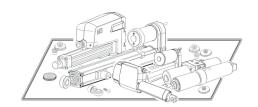
Cell: Email:

Tel.: 0510-85436730 Website: hbactuator.com

Address: 5 Lijiang Rd. Xinwu District, Wuxi 214028 China

You may also be interested in...

Model	Load (N)	Stroke (mm)	Speed (mm/s)	Install.Length (mm)	Overall Size (mm)	IP rate	Application
DJ803 (Track)	1,500	50-600	16-32	155	155 x 77.4 x L	IP20	Furniture
DJ823	3,000	50-600	5.0-15	S+155	148.5 x 80 x L	IP54	Furniture Medical Care
DJ810	4,000	50-600	5.0-32	S+150	156 x 83 x L	IP43	Furniture Medical Care
DJ801	6,000	50-600	4.7-28	S+175	156 x 83 x L	IP43	Furniture Medical Care
DJ822	6,000	50-600	5.0-16	S+175	166 x 91 x L	IP54	Furniture Medical Care
DJ806	1,200	50-600	5.5-80	S+105	40 x 75 x L	IP66	Industrial
DJ809	2,000	50-600	5.0-55	S+108	45 x 77.5 x L	IP66	Industrial
DJ825	2,000	50-600	6-15	S+115	43 x 84.5 x L	IP66	Furniture Medical Care Industrial
DJ820	2,500	50-600	2.5-22	S+120	64.5 x 102 x L	IP66	Furniture Medical Care Industrial
DJ820P	1,000	50-600	25-50	S+140	64.5 x 102 x L	IP66	Industrial
DJ830	4,000	50-600	5.5-35	S+200	76 x 151 x L	IP65	Industrial
DJ830P	7,000	50-600	5.5-35	S+200	76 x 151 x L	IP65	Industrial
* DJ808	7,000	50-600	5.5-35	S+250	77 x 151 x L	IP65	Industrial
DJ805G	12,000	50-1,000	25-100	S+200	102 x 154 x L	IP66	Industrial
DJ812	20,000	50-1,000	5.5-35	S+600	N/A	IP55	Industrial



For more information, please visit our website $\ensuremath{\mathsf{hbactuator}}.\ensuremath{\mathsf{com}}$